Micropolis 4345NS Disk Drive Ultra SCSI (SCSI-3), Narrow, Single-Ended, Standard 50-Pin Connector Configuration/Specification Data Sheet

Formatted Capacity

Per Drive 4.55 GB
Bytes per Sector 512
Sectors per Track Variable
Cylinders 4811

Performance Specifications

Avg. Seek Time (includes settling time)7.9 msecAvg. Rotational Latency4.17 msecRotational Speed7,200 rpm

Data Transfer Rate at Interface

Ultra SCSI 20 MB/sec
Synchronous 10 MB/sec
Asynchronous 5 MB/sec

Internal Data Rate

Inner Zone 76 Mb/sec
Outer Zone 125 Mb/sec

MTBF (power-on hours) 650,000 (Office Environment, Class B)

Positioner Fully balanced rotary voice coil

Parking Automatic park and lock

General Functional Specifications

Interface Ultra SCSI (SCSI-3)

Supports Full Common Command Set Yes

Drivers/Receivers Narrow, Single-Ended

Power Requirements

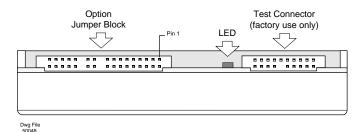
+12V ±5% (average) 0.55 A +12V ±5% (max during start-up) 1.75 A +5V ±5% (average) 1.10 A

Power Dissipation, typical

Idling 10 Watts (34.1 Btu/hr) Seeking 12 Watts (41.0 Btu/hr)

Configuration Options

FRONT VIEW



OPTION JUMPER BLOCK J2
(Front view of the drive, board up)

NOTE: Pins 4, 6, 8, 10, 12, 14, 16, 18, 22, and 24 are tied to Ground.

SCSI ID

Jumpers at Pin 3-4, 5-6, and 7-8 select the SCSI ID. Each SCSI device on one Host Adapter must have a unique SCSI ID (0-7). SCSI ID0 is the Default.

	Pin	Pin	Pin		Pin	Pin	Pin
SCSI ID	7-8	5-6	3-4	SCSI ID	7-8	5-6	3-4
0	_	_	-	4	✓	-	_
1	_	_	✓	5	✓	_	✓
2	_	✓	-	6	✓	✓	_
3	_	✓	✓	7	✓	✓	✓
✓ = ju	mper i	nstalled	1				

• Interface Termination (W4)

Jumper installed at W4 (Default) - The drive provides termination for the interface lines; onboard termination is electrically *enabled*.

Jumper omitted at W4 - The drive does not provide termination for the interface lines; onboard termination is electrically *disabled*.

• Terminator Power (W1, W2, W3)

Jumper installed at W1 (Default) - The drive provides terminator power.

Jumper installed at W2 - The host provides terminator power (via Interface Connector J1A).

Jumper installed at W3 - The drive provides terminator power (via J1A) to the SCSI Bus.

• Spindle Control (SP0)

Jumper installed at SP0, jumper omitted at SP1 - The spindle motor starts when SCSI 'START UNIT' command is received.

Jumpers omitted at SP0 (Default) and at SP1 - The spindle motor starts at power-on.

• Spindle Delay (SP1)

Remote LED-

Jumper installed at SP1, jumper omitted at SP0 Spindle motor start-up is delayed, based on SCSI ID (12 seconds per SCSI ID).

Jumpers omitted at SP1 (Default) and at SP0 - The spindle motor starts at power-on.

• Write Protect (WP)

Jumper installed at WP - The drive is write protected.

Jumper omitted at WP (Default) - The drive is not write protected.

• BUS Parity Check (PTY)

Jumper installed at PTY - The drive neither generates nor detects parity.

Jumper omitted at PTY (Default) - The drive generates parity and has parity detection enabled.

Remote LED

Open-collector output - Used to drive a user-supplied LED to indicate the drive is active.